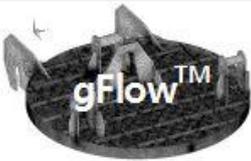
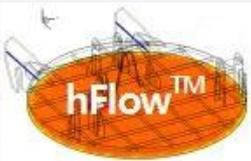
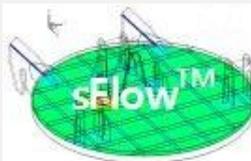
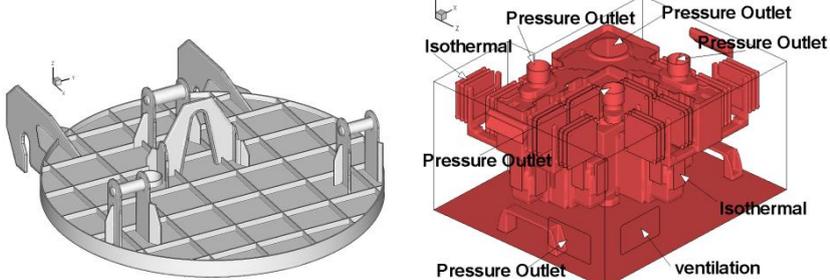


Industrial Machinery Facility Optimization Solution Provider

1. Products

Classification	Contents and Descriptions
 격자생성	<ul style="list-style-type: none"> ● Grid Generation Code ⇒ Using finite difference method ⇒ Structured(including block structured) grid ⇒ Unstructured(including tetrahedral element) grid ⇒ Moving Grid ⇒ Adaptive grid
 열유동해석	<ul style="list-style-type: none"> ● Heat and Fluid Flow Analysis Solver Code ⇒ Combined finite volume with element method ⇒ General coordinate system(body fitted) ⇒ Using iteration method(TDMA matrix solver) ⇒ Central differencing scheme for 2nd order partial derivatives ⇒ 2nd order upwind and QUICK(Quadratic Upstream Interpolation for Convective Kinematics) scheme for 1st order partial derivatives
 응력해석	<ul style="list-style-type: none"> ● Stress Analysis Solver Code(including thermal stress) ⇒ Combined finite difference with element method ⇒ General coordinate system(body fitted) ⇒ Using iteration method(TDMA matrix solver) ⇒ Central differencing scheme for 2nd order partial derivatives ⇒ Central differencing scheme combined with element integration for 2nd order mixed partial derivatives
 최적설계	<ul style="list-style-type: none"> ● Design and Process Optimization Code ⇒ Combined gFlowTM, hFlowTM, sFlowTM with optimization algorithms ⇒ Using ADS(Automated Design Synthesis) optimization code ⇒ Finding single or multi objective value by minimizing error function ⇒ Solving stochastic optimization problem by using the weighted sum approach method

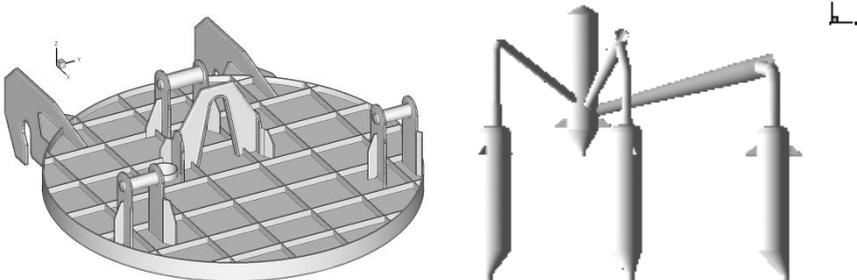
1.1 gFlow™

Classification	Basic Equations and Descriptions
<p>Elliptic Grid Generation Eqn.</p>	$\alpha_{11}^x \xi\xi + \alpha_{12}^x \xi\eta + \alpha_{13}^x \xi\phi + \alpha_{22}^x \eta\eta + \alpha_{23}^x \eta\phi + \alpha_{33}^x \phi\phi = -I^2 (Px\xi + Qx\eta + Rx\phi)$ $\alpha_{11}^y \xi\xi + \alpha_{12}^y \xi\eta + \alpha_{13}^y \xi\phi + \alpha_{22}^y \eta\eta + \alpha_{23}^y \eta\phi + \alpha_{33}^y \phi\phi = -I^2 (Py\xi + Qy\eta + Ry\phi)$ $\alpha_{11}^z \xi\xi + \alpha_{12}^z \xi\eta + \alpha_{13}^z \xi\phi + \alpha_{22}^z \eta\eta + \alpha_{23}^z \eta\phi + \alpha_{33}^z \phi\phi = -I^2 (Pz\xi + Qz\eta + Rz\phi)$
<p>Jacobian</p>	$I = x\xi(y\eta z\phi - y\phi z\eta) - x\eta(y\xi z\phi - y\phi z\xi) + x\phi(y\xi z\eta - y\eta z\xi)$
<p>Matrix Tensor</p>	$\alpha_{11} = \beta_{11}^2 + \beta_{21}^2 + \beta_{31}^2, \alpha_{12} = \beta_{11}\beta_{12} + \beta_{21}\beta_{22} + \beta_{31}\beta_{32}$ $\alpha_{13} = \beta_{11}\beta_{13} + \beta_{21}\beta_{23} + \beta_{31}\beta_{33}, \alpha_{22} = \beta_{12}^2 + \beta_{22}^2 + \beta_{32}^2$ $\alpha_{23} = \beta_{12}\beta_{13} + \beta_{22}\beta_{23} + \beta_{32}\beta_{33}, \alpha_{33} = \beta_{13}^2 + \beta_{23}^2 + \beta_{33}^2$
<p>Invariants</p>	$\beta_{11} = y\eta z\phi - y\phi z\eta, \beta_{12} = y\phi z\xi - y\xi z\phi, \beta_{13} = y\xi z\eta - y\eta z\xi$ $\beta_{21} = x\phi z\eta - x\eta z\phi, \beta_{22} = x\xi z\phi - x\phi z\xi, \beta_{23} = x\eta z\xi - x\xi z\eta$ $\beta_{31} = x\eta y\phi - x\phi y\eta, \beta_{32} = x\phi y\xi - x\xi y\phi, \beta_{33} = x\xi y\eta - x\eta y\xi$
<p>Control Function Thomas & Middlecoff</p>	$P = x\xi\xi + x\eta\eta + x\phi\phi, Q = y\xi\xi + y\eta\eta + y\phi\phi, R = z\xi\xi + z\eta\eta + z\phi\phi$
<p>Case Analysis</p>	

1.2 hFlow™

Classification	Basic Equations and Descriptions
Continuity Eqn.	$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_j} (\rho u_j) = 0$
Momentum Eqn.	$\frac{\partial}{\partial t} (\rho u_i) + \frac{\partial}{\partial x_j} (\rho u_j u_i) = \rho f_i - \frac{\partial p}{\partial x_i} + \frac{\partial \tau_{ij}}{\partial x_j}$ $f_i = \text{body force}$
Energy Eqn.	$\frac{\partial}{\partial t} (\rho H - p) + \frac{\partial}{\partial x_j} (\rho u_j H) = -\frac{\partial q_j}{\partial x_j} + \frac{\partial}{\partial x_j} (u_j \tau_{ij})$ $H = C_p T + \frac{1}{2} (u_1^2 + u_2^2 + u_3^2), \quad q_j = -k \frac{\partial T}{\partial x_j}$
2-eqns. Turbulence Model	$\frac{\partial}{\partial t} (\rho \Phi) + \frac{\partial}{\partial x_i} (\rho u_i \Phi) = \frac{\partial}{\partial x_i} \left(\Gamma \Phi \frac{\partial \Phi}{\partial x_i} \right) + R_1 + R_2$ $R_1 = \Pi \text{ or } \frac{C_1 \epsilon \Pi}{k}, \quad R_2 = -\left(\frac{C_\mu \rho^2 k^*}{\mu_t} \right) k \text{ or } -\left(\frac{C_2 \rho \epsilon^*}{k^*} \right) \epsilon$ $\Pi = \left[\mu_t \left(\frac{\partial \langle u_i \rangle}{\partial x_j} + \frac{\partial \langle u_j \rangle}{\partial x_i} \right) - p \delta_{ij} \right] \frac{\partial \langle u_i \rangle}{\partial x_j}, \quad \mu_t = \frac{C_\mu f \mu \rho \kappa^2}{\epsilon}$
Stress Tensor	$\tau_{ij} = \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \frac{\partial u_k}{\partial x_k} \right), \quad \delta_{ij} = \text{Kronecker's Delta}$
Case Analysis	<p>The Case Analysis section contains two diagrams. The left diagram shows a piping system with components labeled CP-101, CP-102, CP-103, BP-101, Oil Pump Return, and Oil Pump Supply. A legend identifies symbols for Check Valve (black square), Ball/Globe Valve (green square), Flow Meter (blue square), and Control Valve (red square). The right diagram shows a 3D mesh of a turbine-like structure with flow boundaries labeled: Outflow (Outdoor), Inflow (Indoor), Inflow (Outdoor), and Outflow (Indoor). It also features a Guide Vane and a Rib.</p>

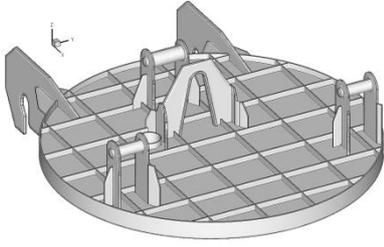
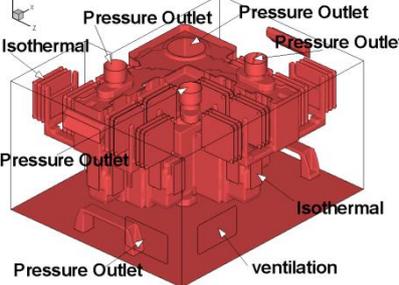
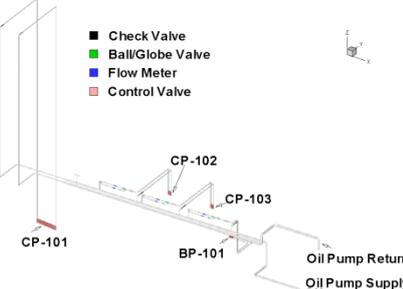
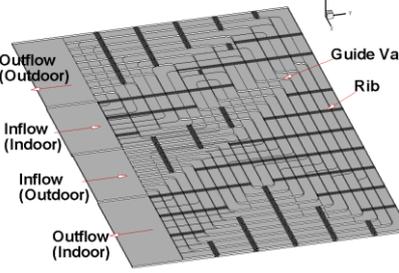
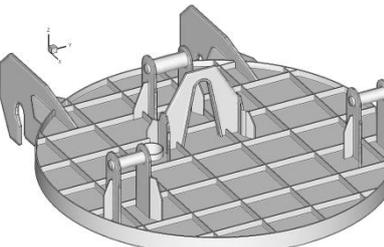
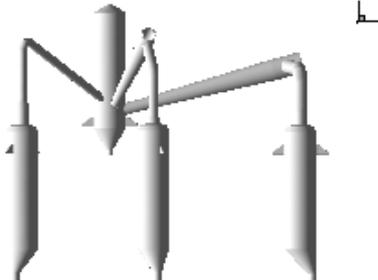
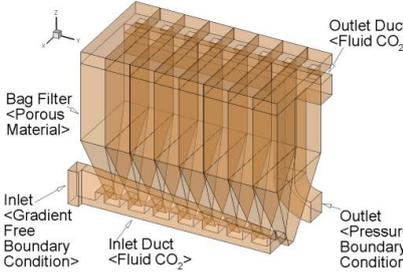
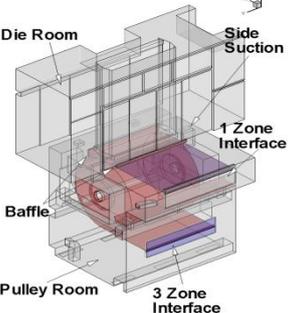
1.3 sFlow™

Classification	Basic Equations and Descriptions
Equilibrium Eqn.	$(\lambda+G)\frac{\partial}{\partial x_i}\left(\frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}+\frac{\partial w}{\partial z}\right)+G\left(\frac{\partial^2 u}{\partial x^2}+\frac{\partial^2 v}{\partial y^2}+\frac{\partial^2 w}{\partial z^2}\right)=\frac{\alpha E}{1-2\nu}\frac{\partial T}{\partial x_i}-X_i$
Modulus of Elasticity	$G=\frac{E}{2(1+\nu)}, \lambda=\frac{\nu E}{(1+\nu)(1-2\nu)}$
Strain Rates	$\epsilon_x=\frac{\partial u}{\partial x}, \epsilon_y=\frac{\partial v}{\partial y}, \epsilon_z=\frac{\partial w}{\partial z}, \epsilon=\epsilon_x+\epsilon_y+\epsilon_z$ $\gamma_{xy}=\frac{\partial u}{\partial y}+\frac{\partial v}{\partial x}, \gamma_{xz}=\frac{\partial u}{\partial z}+\frac{\partial w}{\partial x}, \gamma_{yz}=\frac{\partial v}{\partial z}+\frac{\partial w}{\partial y}$
Stresses	$\sigma_x=\frac{\nu E}{(1+\nu)(1-2\nu)}\epsilon+\frac{E}{1+\nu}\epsilon_x, \tau_{xy}=G\gamma_{xy}$ $\sigma_y=\frac{\nu E}{(1+\nu)(1-2\nu)}\epsilon+\frac{E}{1+\nu}\epsilon_y, \tau_{yz}=G\gamma_{yz}$ $\sigma_z=\frac{\nu E}{(1+\nu)(1-2\nu)}\epsilon+\frac{E}{1+\nu}\epsilon_z, \tau_{zx}=G\gamma_{zx}$
Principal Stress	$\sigma^3-I_1\sigma^2+I_2\sigma-I_3=0$ $I_1=\sigma_x+\sigma_y+\sigma_z=\sigma_1+\sigma_2+\sigma_3$ $I_2=\sigma_y\sigma_z+\sigma_z\sigma_x+\sigma_x\sigma_y-\tau_{yz}^2-\tau_{xz}^2-\tau_{xy}^2=\sigma_2\sigma_3+\sigma_3\sigma_1+\sigma_1\sigma_2$ $I_3=\begin{vmatrix} \sigma_x & \tau_{yx} & \tau_{zx} \\ \tau_{xy} & \sigma_y & \tau_{zy} \\ \tau_{xz} & \tau_{yz} & \sigma_z \end{vmatrix}=\sigma_1\sigma_2\sigma_3$
Failure Criteria Von Mises & Hencky	$\tau_0 = \left(\frac{1}{9} \left[(\sigma_x - \sigma_y)^2 + (\sigma_x - \sigma_z)^2 + (\sigma_z - \sigma_x)^2 + 6\tau_{xy}^2 + 6\tau_{xz}^2 + 6\tau_{yz}^2 \right] \right)^{\frac{1}{2}}$ $= \frac{\sqrt{2}}{3} Y$
Fatigue Life (Basquin)	$\frac{\Delta\sigma}{2} = \sigma_f (2N_f)^b$ $\frac{\Delta\sigma}{2}$ = true stress amplitude , $2N_f$ = the number of reversals to failure , σ_f = fatigue strength coefficient , b = fatigue strength exponent
Case Analysis	

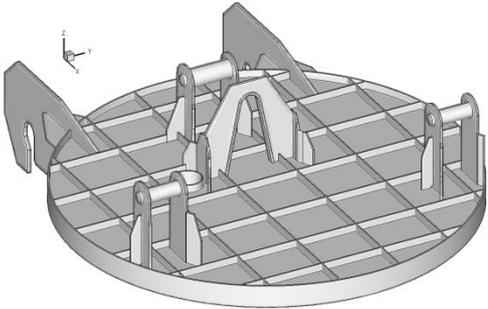
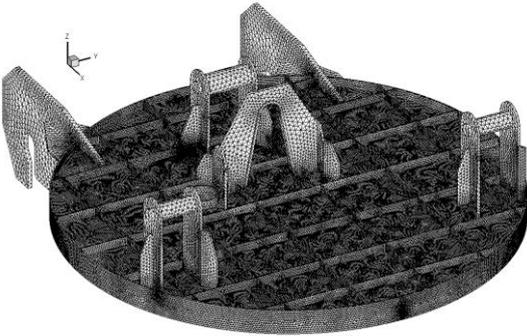
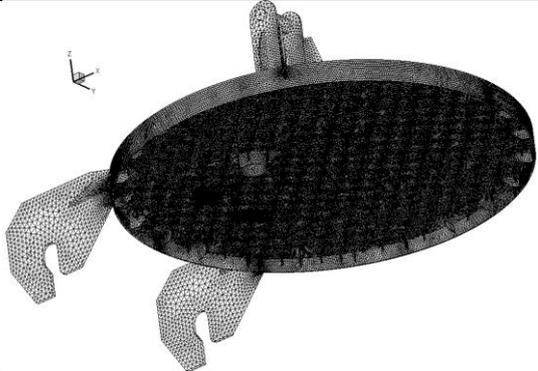
1.4 aFlow™

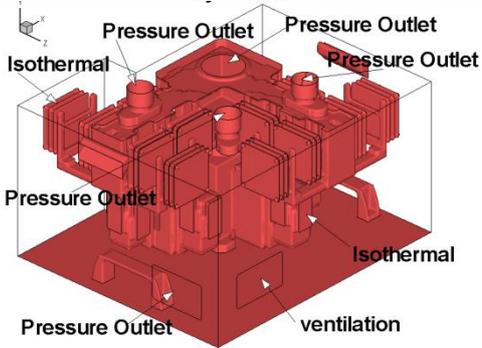
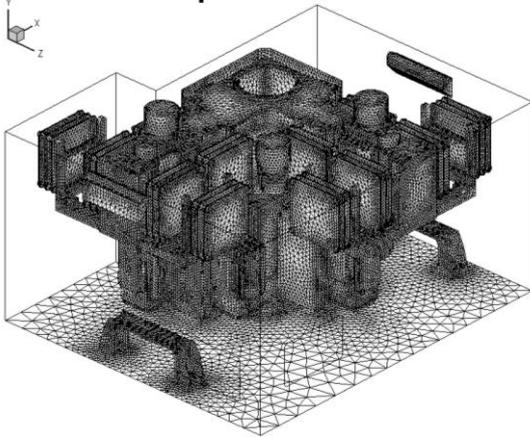
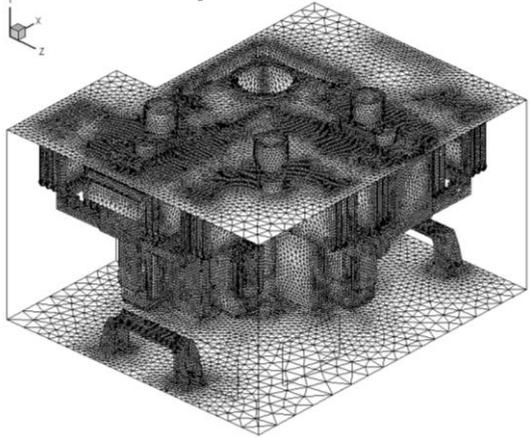
Classification	Basic Equations and Descriptions
<p>Single Objective Function</p>	<p><i>Minimize</i> $f(x)$</p> $f(x) = w_1 f_1(x) + w_2 f_2(x) + \dots + w_m f_m(x)$ <p><i>Subject to</i> $g_j(x) \leq 0, \quad j = 1, 2, K, J$</p> $h_k(x) = 0, \quad k = 1, 2, K, K$ $x_i^{(L)} \leq x_i \leq x_i^{(U)}, \quad i = 1, 2, K, N$
<p>Multi-Objective Function</p>	<p><i>Minimize</i> $(f_1(x), f_2(x), K, f_M(x))$</p> <p><i>Subject to</i> $g_j(x) \leq 0, \quad j = 1, 2, K, J$</p> $h_k(x) = 0, \quad k = 1, 2, K, K$ $x_i^{(L)} \leq x_i \leq x_i^{(U)}, \quad i = 1, 2, K, N$ <p><i>Feasible Solution</i> $f_i^a \leq f_i^b$ for all $i = 1, 2, K, M$</p> $f_i^a \leq f_i^b$ for at least one $i \in \{1, M\}$
<p>Stochastic Optimization Problem</p>	<p><i>Minimize</i> $f_m(\mu_{ym}(x), \sigma_{ym}(x)), \quad m = 1, 2, K, M$</p> <p><i>Subject to</i> $g_j(\mu_{yj}(x), \sigma_{yj}(x)) \leq 0, \quad j = 1, 2, K, J$</p> $h_k(x) = 0, \quad k = 1, 2, K, K$ $x_i^{(L)} + n\sigma_{xi} \leq x_i \leq x_i^{(U)} - n\sigma_{xi}, \quad i = 1, 2, K, N$ <p><i>Constraints</i> $\mu_y - n\sigma_y \geq \text{Lower Limit}$</p> $\mu_y + n\sigma_y \geq \text{Upper Limit}$
<p>Optimizing Algorithms</p>	<ul style="list-style-type: none"> ● One dimensional search ● Fletcher-Reeves algorithm for unconstrained minimization ⇒ Davidon-Fletcher-Powell variable metric method for unconstrained minimization ⇒ Broydon-Fletcher-Goldfarb-Shanno variable metric method for unconstrained minimization ● Method of Feasible Direction for constrained minimization
<p>Case Analysis</p>	

2. Case Analysis

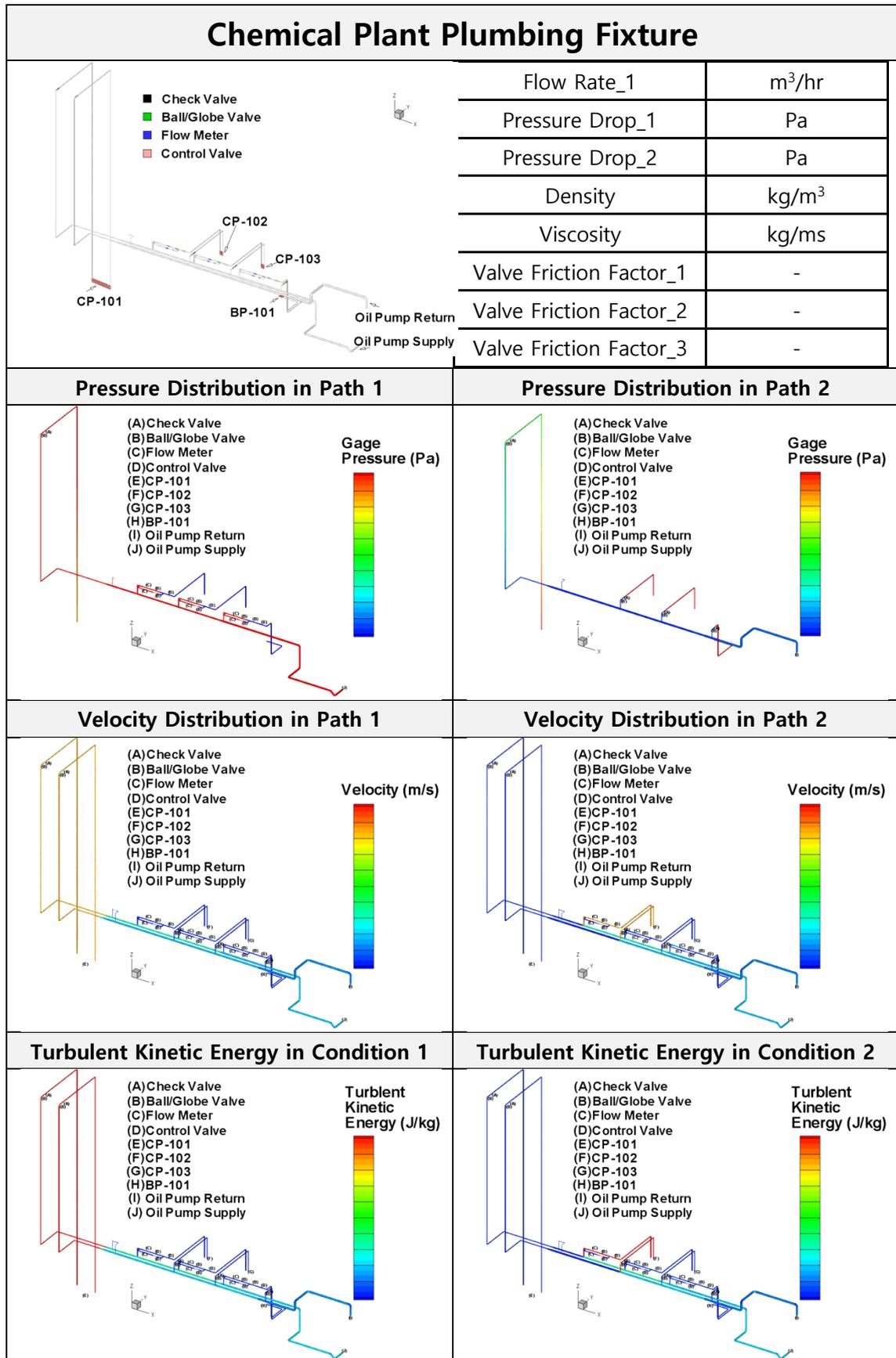
Classification	Simulation Case	
<p>Grid Generation</p>		
	<p>Tetrahedral Adaptive Mesh</p>	
<p>Heat and Fluid Flow</p>		
	<p>Fluid Flow</p>	<p>Heat and Fluid Flow</p>
<p>Thermal Stress</p>		
	<p>Fatigue Failure</p>	<p>Thermal Stress</p>
<p>Design Optimization</p>		
	<p>Design Optimization</p>	<p>Process Optimization</p>

2.1 Grid Generation

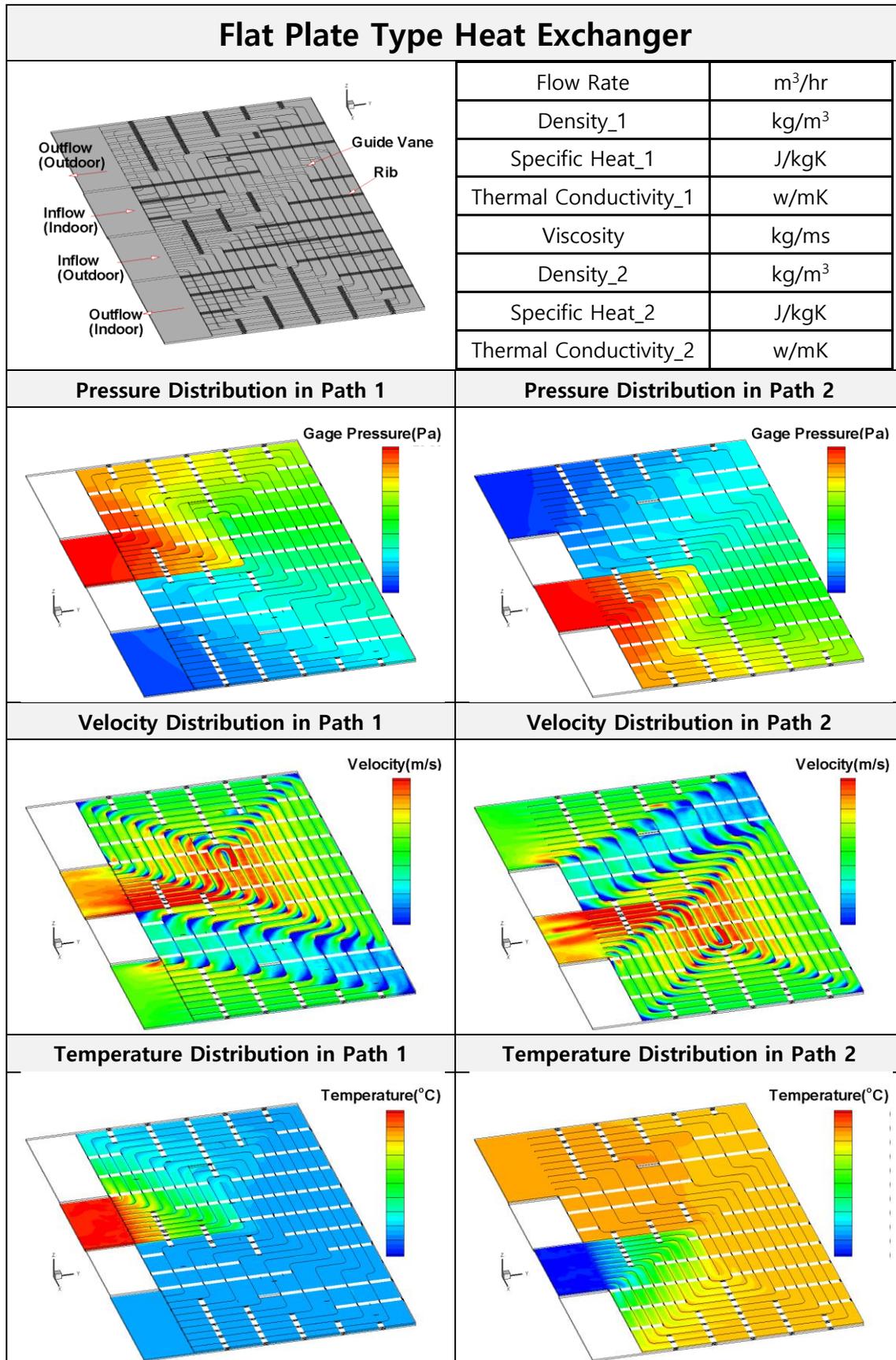
Ladle Metallurgical Furnace Cover		
	Temperature	°C
	Design Temperature	°C
	Heat Transfer Coef._1	W/m ² K
	Heat Transfer Coef._2	W/m ² K
	Density	kg/m ³
	Specific Heat	J/kgK
	Thermal Conductivity	W/mK
	Initial Condition	°C

Vision Inspection Module		
	Design Condition	°C
	Density_1	kg/m ³
	Viscosity_1	kg/ms
	Pressure Drop	Pa
	Heat Source_1	°C
	Heat Source_2	°C
	Initial Condition	°C
	Initial Condition	°C

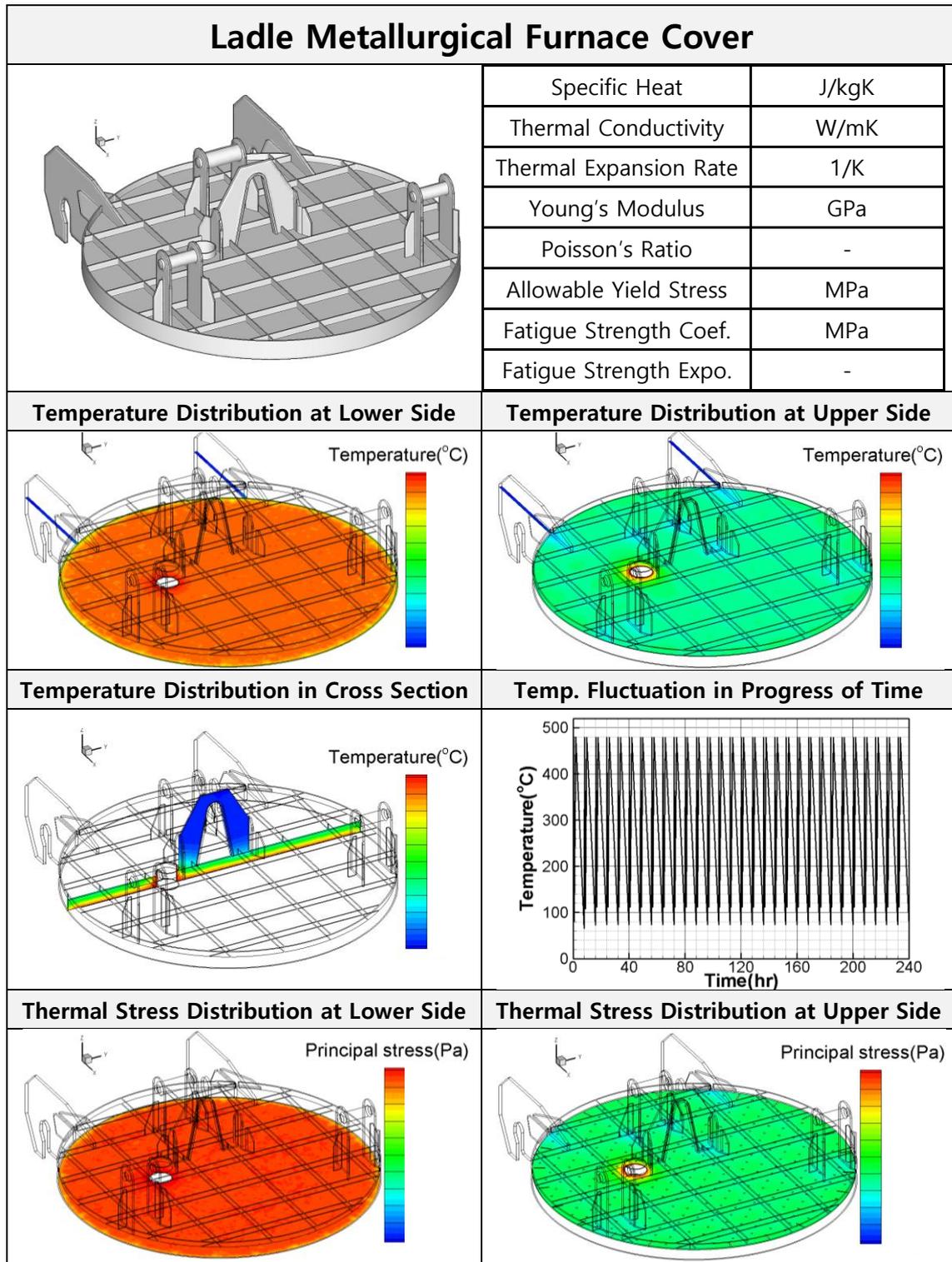
2.2 Fluid Flow Analysis



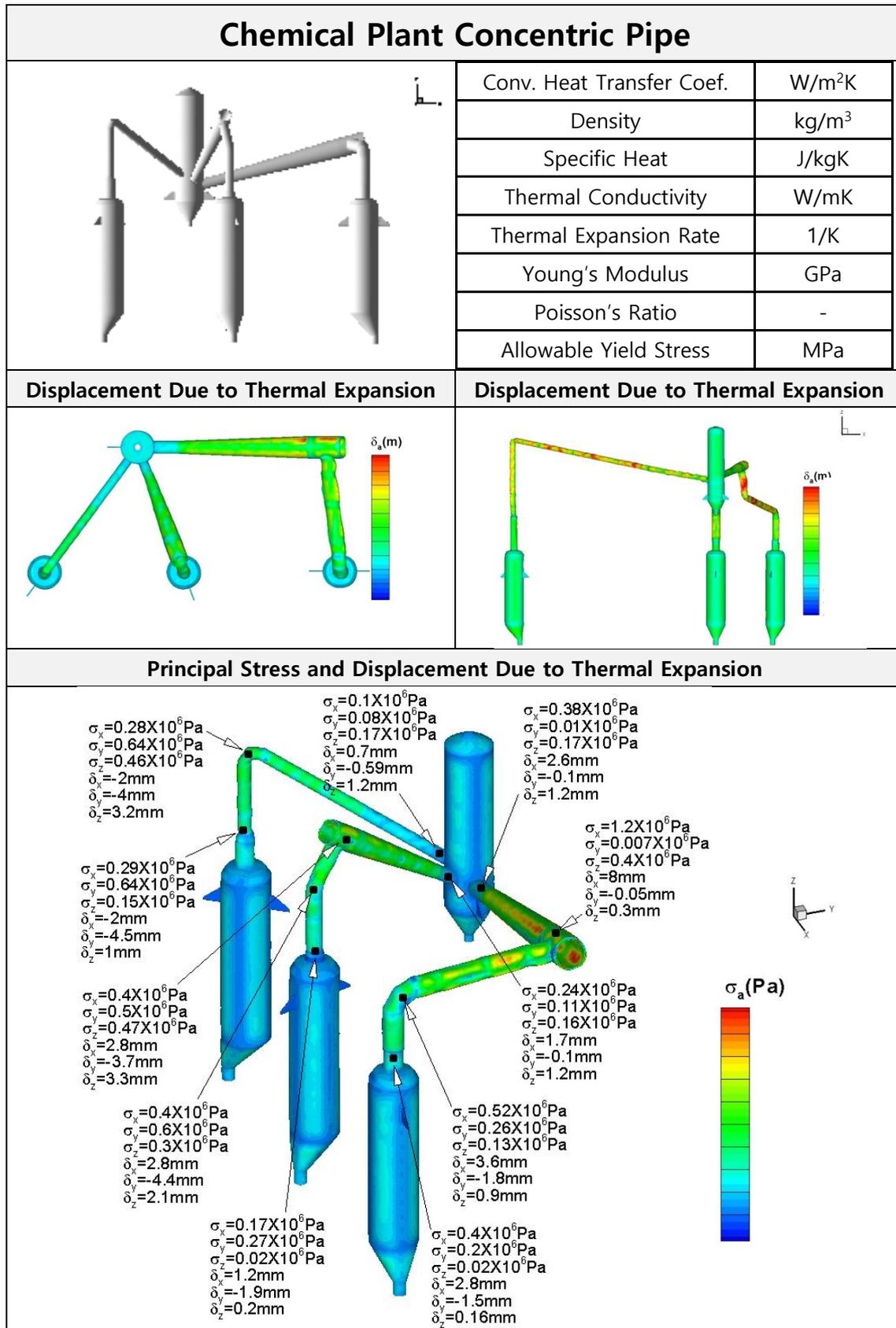
2.3 Heat and Fluid Flow Analysis



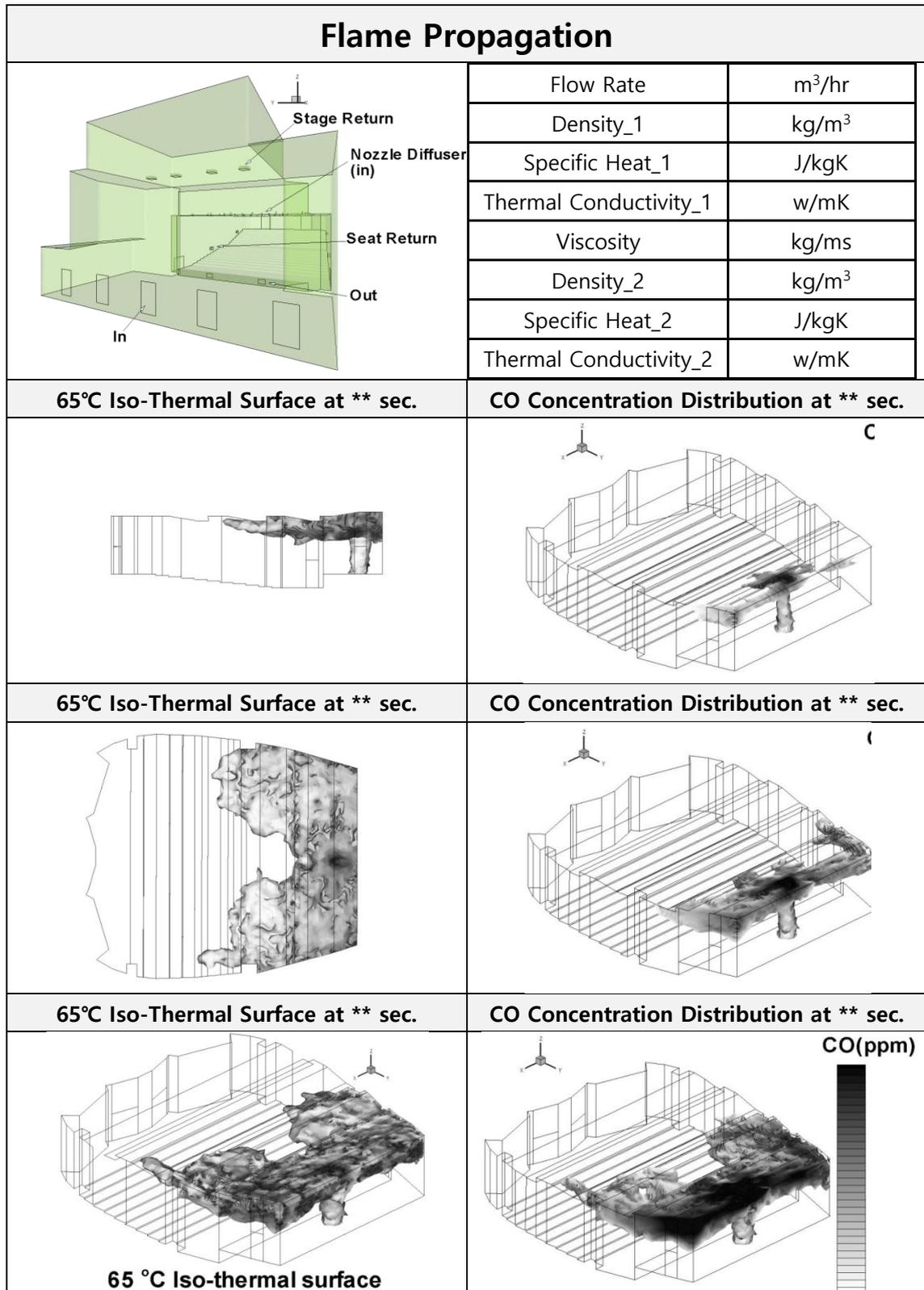
2.4 Fatigue Failure and Life Analysis



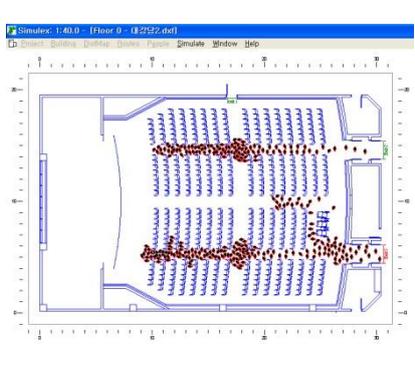
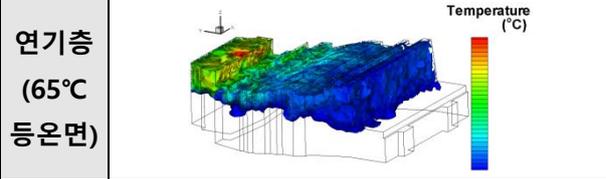
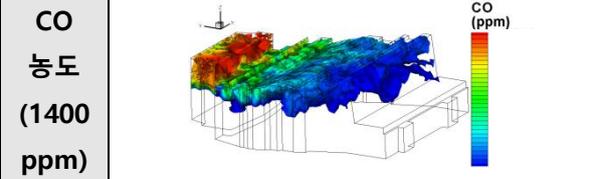
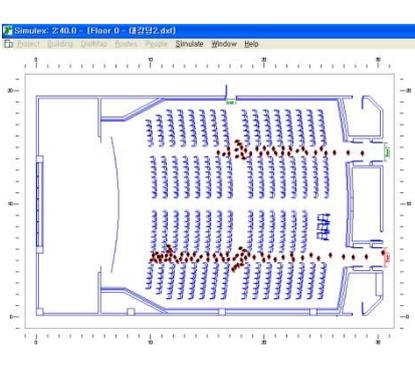
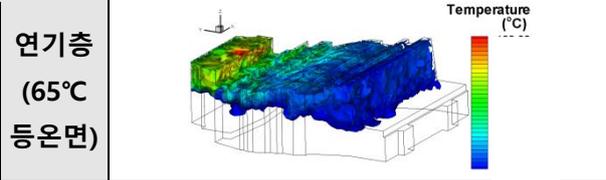
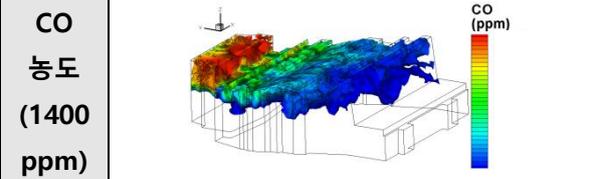
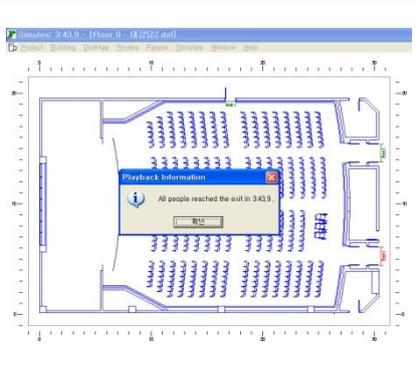
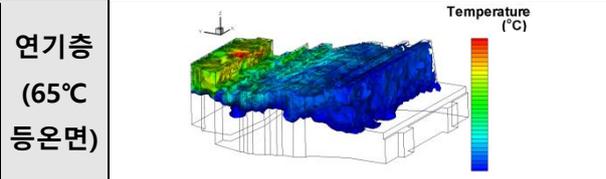
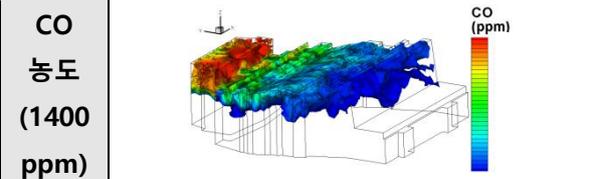
2.5 Thermal Stress Analysis



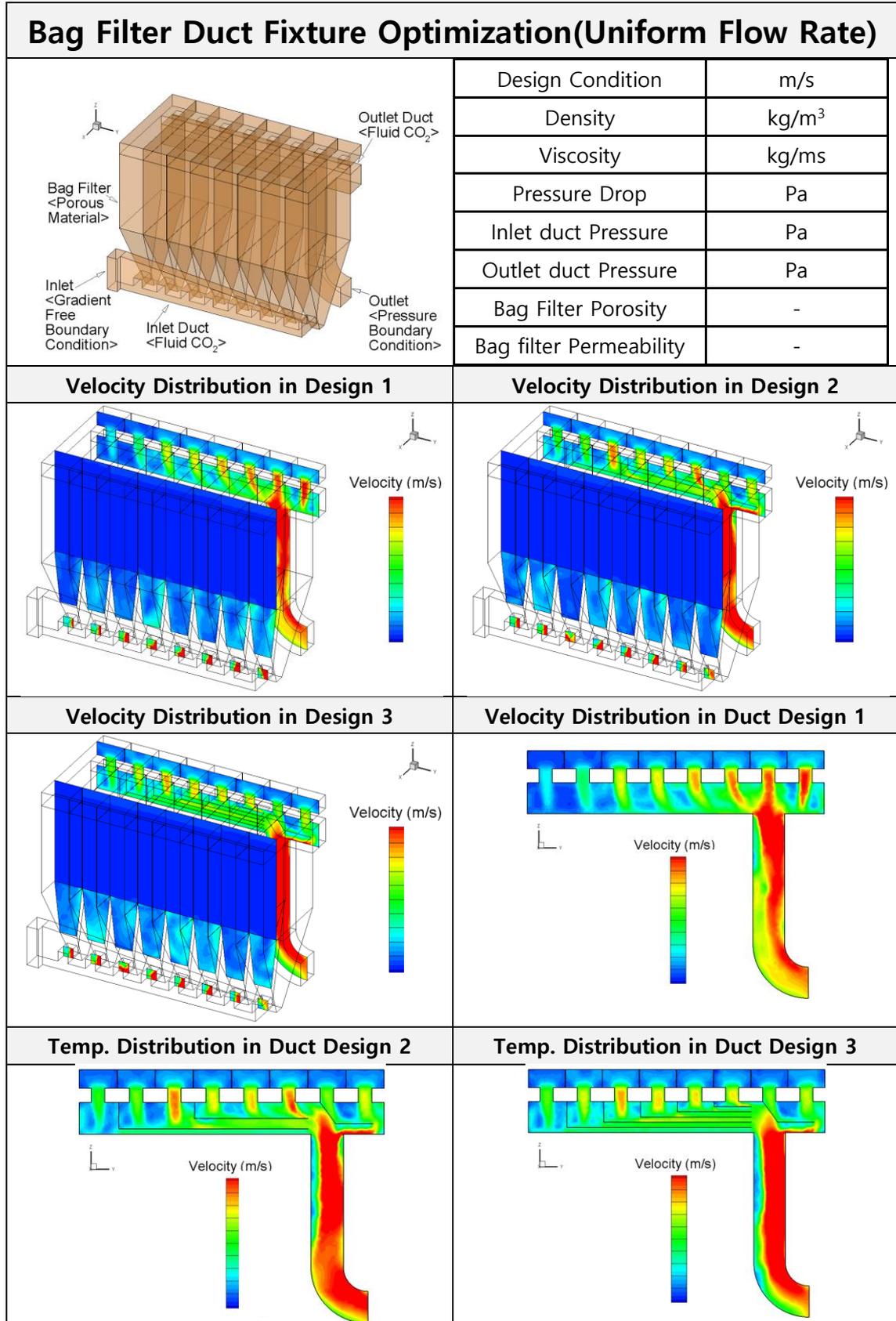
2.6 Mass Transfer Analysis



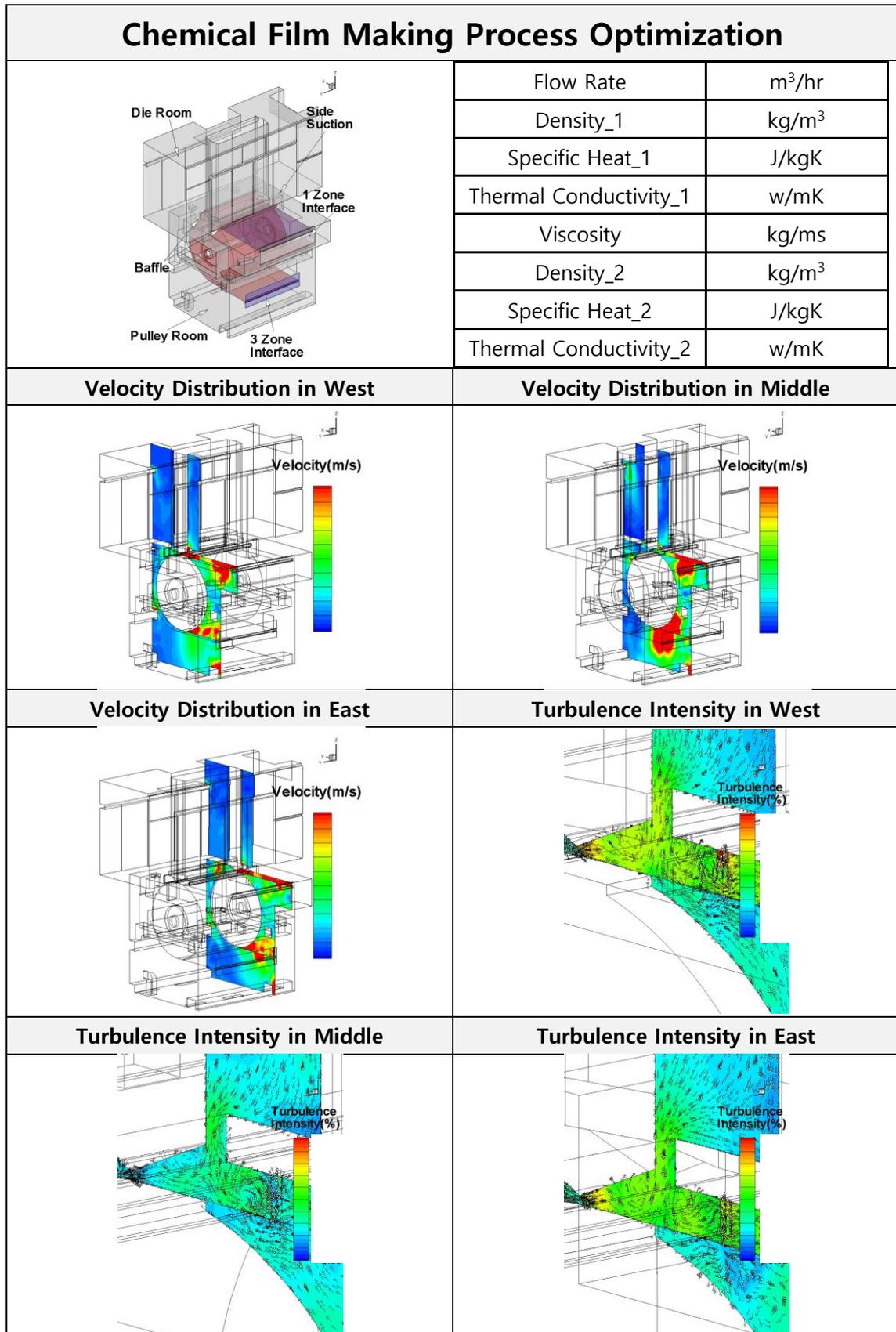
2.7 Fire Emission and Evacuation

진행	피난시뮬레이션		화재시뮬레이션		
	*분 **초		연기층 (65°C 등온면)		Temperature (°C)
		CO 농도 (1400 ppm)		CO (ppm)	
*분 **초		연기층 (65°C 등온면)		Temperature (°C)	
		CO 농도 (1400 ppm)		CO (ppm)	
*분 **초		연기층 (65°C 등온면)		Temperature (°C)	
		CO 농도 (1400 ppm)		CO (ppm)	
검토 결과	<p>. 재실인원이 모두 피난 완료할 때까지 연기층(65°C) 위치가 피난출구 바닥면에서 2m 높이에 도달하여 피난안전성 확보함.</p> <p>. CO 가스 농도(1400ppm)의 위치도 피난 완료시까지 피난출구 바닥면에서 2.3m 높이에 도달하여 피난안전성 확보함.</p>				
구분	피난 인원 (명)	피난 및 화재시뮬레이션			판정
		피난소요시간 (RSET)	피난가능시간(ASET)		
			연기층(65°C)	CO 농도 1400ppm	
000 화재	000	0 분 00 초	0 분 00 초	0 분 00 초	안전

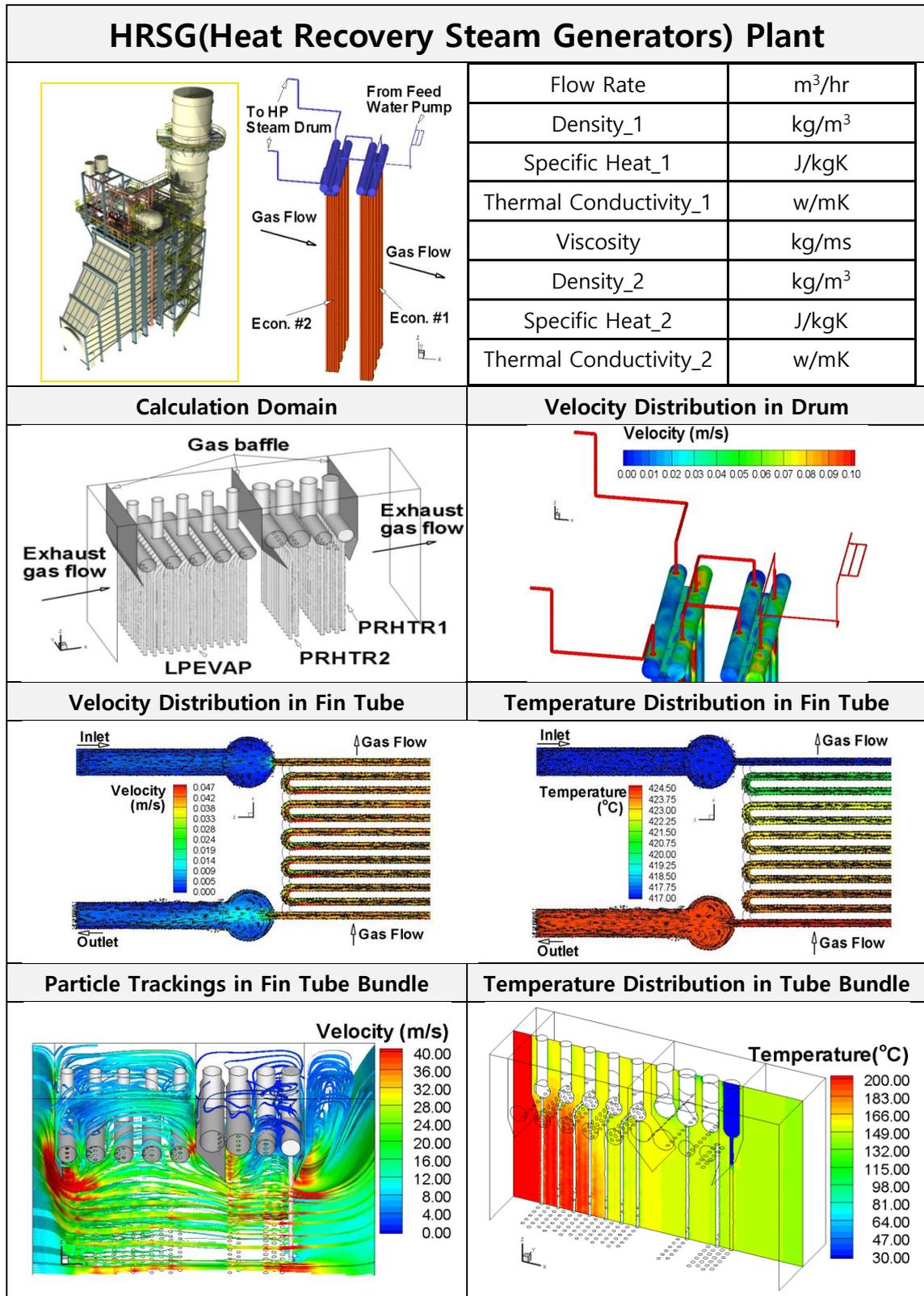
2.8 Design Optimization



2.9 Process Optimization 1



2.10 Process Optimization 2



3. CONTACT US

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2026년 월 일

hFlow

CFD Solution Group

대표 김소영
공학박사 윤정배